

Varun Sreedhara Bhatt

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Research Interests: Open-Ended Learning, Quality Diversity Optimization, Reinforcement Learning, Multi-Agent Systems, Human-Robot Collaboration

EDUCATION

Doctor of Philosophy (Computer Science) | University of Southern California | **GPA: 4/4** [2021-Present]

• Training generally capable intelligent agents by leveraging quality diversity optimization and scenario generation

Master of Science (Computing Science) | University of Alberta | GPA: 3.9/4 [2018-2020]

- **Thesis:** Inference-Based Deterministic Messaging for Multi-Agent Communication (supervised by Prof. Michael Buro)
 - Identified issues with multi-agent reinforcement learning methods when learning to communicate
 - Proposed a method based on simulating Bayesian inference of private state for guiding agent's messages

Bachelor of Technology (Electrical Engg) | Indian Institute of Technology Bombay | GPA: 9.55/10 [2014-2018]

- Minor in Computer Science (GPA: 10/10)
- **Project:** Unsupervised Learning Using Sparse Coding in Spiking Convolutional Neural Networks (supervised by Prof. Udayan Ganguly)
 - Extended the idea of sparse coding into spiking convolutional neural networks
 - Showed improvements in data and energy efficiency compared to traditional CNNs

PUBLICATIONS, PATENTS, AND PRE-PRINTS

- Zhang, Y., Jiang, H., Bhatt, V., Nikolaidis, S., and Li, J. "Guidance Graph Optimization for Lifelong Multi-Agent Path Finding,". *arXiv preprint arXiv:2402.01446*. (Accepted at IJCAI 2024). Arxiv link
- Zhang, Y., Fontaine, M. C., Bhatt, V., Nikolaidis, S., and Li, J. "Arbitrarily Scalable Environment Generators via Neural Cellular Automata," in *Advances in Neural Information Processing Systems (NeurIPS)*, 2023. Arxiv link.
- Bhatt, V., Nemlekar, H., Fontaine, M.C., Tjanaka, B., Zhang, H., Hsu, Y. C., and Nikolaidis, S. "Surrogate Assisted Generation of Human-Robot Interaction Scenarios," in *Proceedings of the Conference on Robot Learning (CoRL)*, 2023. Oral Presentation. Arxiv link.
- Zhang, Y., Fontaine, M. C., Bhatt, V., Nikolaidis, S., and Li, J. "Multi-Robot Coordination and Layout Design for Automated Warehousing," in *Proceedings of the International Joint Conference on Artificial Intelligence (IJCAI)*, 2023. Arxiv link.
- Bhatt, V.*, Tjanaka, B.*, Fontaine, M. C.*, and Nikolaidis, S. "Deep Surrogate Assisted Generation of Environments," in Advances in Neural Information Processing Systems (NeurIPS), 2022. Arxiv link.
- Bhatt, V. and Buro, M. "Inference-based Deterministic Messaging For Multi-Agent Communication," in *Proceedings of the 35th AAAI Conference on Artificial Intelligence, 2021.* (also accepted at *the AAAI Workshop on Reinforcement Learning in Games, 2021*). Arxiv link.
- Kalyanakrishnan, S., Aravindan, S.*, Bagdawat, V.*, **Bhatt, V.***, Goka, H.*, Gupta, A.*, Krishna, K.*, and Piratla, V.* "An Analysis of Frame-skip in Reinforcement Learning," *arXiv preprint arXiv:2102.03718*, 2021. Arxiv link.
- Bhatt, V., Shrivastava, S., Chavan, T., and Ganguly, U. "Software-Level Accuracy Using Stochastic Computing With Charge-Trap-Flash Based Weight Matrix," in *Proceedings of the International Joint Conference on Neural Networks (IJCNN)*, 2020. Arxiv link.
- Shrivastava, S., Chavan, T., **Bhatt, V.**, and Ganguly, U. "Flash Memory for Low Energy Synapse," an Indian Patent Application (Number 201921006118).
- Bhatt, V., and Ganguly, U. "Sparsity Enables Data and Energy Efficient Spiking Convolutional Neural Networks," in *Proceedings of the 27th International Conference on Artificial Neural Networks (ICANN)*, 2018.

WORK EXPERIENCE

Research Assistant <i>Prof. James Wright, University of Alberta, Canada</i> [S	ep 2020-Aug 2021]
 Worked on modelling human behaviour in strategic games 	
 Collected human behaviour data using Amazon Mechanical Turk and analyzed it through behavioural game theory models 	
Internships	
Samsung Electronics South Korea	[May-July 2017]
 Created a prototype for a smart home monitoring system using anomaly detection Received a pre-placement offer based on the work done during the internship 	
• Philips India	[May-July 2016]
 Developed a framework to automatically generate lip-sync animations and emotions in a 3D avatar given a text to speak, as a part of a virtual chatbot 	
Teaching Assistantship	
• Deep Learning and its Applications, University of Southern California	[Spring 2024]
Introduction to Robotics, University of Southern California	[Fall 2023]
• Intelligent Agents, University of Alberta	[Winter 2020]

- Reinforcement Learning Specialization, University of Alberta on Coursera [2019-2020]
- Introduction to the Foundations of Computation, University of Alberta [Fall 2018, Winter 2019, Fall 2019]
- Partial Differential Equations, Indian Institute of Technology Bombay
 [Autumn 2016]

OTHER TALKS

- "Quality Diversity Scenario Generation for Robust Intelligent Agents" at USC Theta Tau Professor Research Event, 2024, on behalf of the ICAROS Lab.
- Introduction to **"Environment Generation for Generalizable Robots (EGG)"** at EGG workshop at RSS 2023.
- Talk on **"Training Multiple Intelligent Agents to Communicate"** at the Tea Time Talks 2019, Department of Computing Science, University of Alberta (video available on YouTube)
- Joint talk with Arta Seify on **"The StarCraft 2 ML Environment"** at the AIIDE-18 Workshop on Artificial Intelligence for Strategy Games
- The project "Smart Room" was selected as the best project in the category of reproducibility at Tech & RnD Exposition 2015, IIT Bombay

OUTREACH

- Represented ICAROS Lab in the Robotics Open House 2024, showing robot demos to K-12 students.
- Led the organization of the first workshop on "Environment Generalizable Robots (EGG)" at RSS 2023.
- Conference/Journal reviews: GECCO 2023, EGG workshop at RSS 2023, ALOE workshop at NeurIPS 2023, HRI 2024, GECCO 2024, TEVC-IEEE

TECHNICAL SKILLS

- **Programming Languages:** Python, C/C++
- Libraries: PyTorch, TensorFlow, NumPy, Pandas, Jax, ROS, Isaac Sim